## Measurements

<table>
<thead>
<tr>
<th>Measurements</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>mean signal (mean)</td>
<td>1544.3</td>
</tr>
<tr>
<td>Signal to Noise Ratio (SNR)</td>
<td>233.4</td>
</tr>
<tr>
<td>Signal to Fluctuation Ratio (SFNR)</td>
<td>228.9</td>
</tr>
<tr>
<td>Percent Fluctuation</td>
<td>0.05</td>
</tr>
<tr>
<td>Drift</td>
<td>0.35</td>
</tr>
<tr>
<td>Radius of Decorrelation (RDC)</td>
<td>8.3</td>
</tr>
<tr>
<td>Mean Ghost Percentage</td>
<td>1.996</td>
</tr>
<tr>
<td>Standard Deviation (std)</td>
<td>0.80</td>
</tr>
</tbody>
</table>

## Signal

![Signal graph](image-url)
Frequence Spectrum

[mean, SNR, SFNR] = [1544.3 233.4 228.9]

Raduis of Decorrelation

rdc = 9.3 pixels
Smoothness - X

Smoothness (FWHM) in mm - X: [min mean max] = [2.047 2.155 2.229]

Smoothness - Y

Smoothness (FWHM) in mm - Y: [min mean max] = [2.379 2.441 2.522]
Smoothness - Z

Smoothness (FWHM) in mm - Z: [min mean max] = [1.497 1.719 1.896]

Center of Mass - X

Center of Mass in mm - X: [max displacement drift] = [0.016 -0.016]
Center of Mass - Y

Center of Mass in mm - Y: [maxdisplacement drift] = [0.048 0.045]

Center of Mass - Z

Center of Mass in mm - Z: [maxdisplacement drift] = [0.032 0.025]
Ghost

Mean of ghost voxels as % of non-ghost [masked] mean
(ghostmean, brightghostmean) = (1.996, 4.775)
(lower is better)

Odd-Even Difference Image