Measurements

<table>
<thead>
<tr>
<th>Measurements</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>mean signal (mean)</td>
<td>2607.5</td>
</tr>
<tr>
<td>Signal to Noise Ratio (SNR)</td>
<td>192.2</td>
</tr>
<tr>
<td>Signal to Fluctuation Ratio (SFNR)</td>
<td>196.8</td>
</tr>
<tr>
<td>Percent Fluctuation</td>
<td>0.05</td>
</tr>
<tr>
<td>Drift</td>
<td>0.42</td>
</tr>
<tr>
<td>Radius of Decorrelation (RDC)</td>
<td>10.0</td>
</tr>
<tr>
<td>Mean Ghost Percentage</td>
<td>2.345</td>
</tr>
<tr>
<td>Standard Deviation (std)</td>
<td>1.39</td>
</tr>
</tbody>
</table>

Signal

result.xml [percent fluct (trend removed), drift, driftfit] = [0.05, 0.42, 0.]

![Signal graph with observed and fit lines](image-url)
Frequence Spectrum

[mean, SNR, SFMR] = [2607.5 192.2 196.8]

Raduis of Decorrelation

rdc = 10.0 pixels
Smoothness - X

Smoothness (FWHM) in mm - X: [min mean max] = [2.171 2.272 2.390]

Smoothness - Y

Smoothness (FWHM) in mm - Y: [min mean max] = [2.470 2.546 2.651]
Smoothness - Z

Smoothness (FWHM) in mm - Z: [min mean max] = [1.507 1.953 2.327]

Center of Mass - X

Center of Mass in mm - X: [max displacement drift] = [0.04] -0.005]
Center of Mass - Y

Center of Mass in mm - Y: [max displacement drift] = [0.070 0.008]

Center of Mass - Z

Center of Mass in mm - Z: [max displacement drift] = [0.029 0.005]
Ghost

Mean of ghost voxels as % of non-ghost [masked] mean
(ghostmean, brightghostmean) = (2.345, 4.951)
(lower is better)

Odd-Even Difference Image