Measurements

<table>
<thead>
<tr>
<th>Measurements</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>mean signal (mean)</td>
<td>2688.6</td>
</tr>
<tr>
<td>Signal to Noise Ratio (SNR)</td>
<td>187.4</td>
</tr>
<tr>
<td>Signal to Fluctuation Ratio (SFNR)</td>
<td>188.4</td>
</tr>
<tr>
<td>Percent Fluctuation</td>
<td>0.06</td>
</tr>
<tr>
<td>Drift</td>
<td>0.47</td>
</tr>
<tr>
<td>Radius of Decorrelation (RDC)</td>
<td>8.9</td>
</tr>
<tr>
<td>Mean Ghost Percentage</td>
<td>2.172</td>
</tr>
<tr>
<td>Standard Deviation (std)</td>
<td>1.49</td>
</tr>
</tbody>
</table>

Signal

graph [percent fluct (trend removed), drift, driftfit] = [0.06, 0.47, 0.]

Frame number
Frequence Spectrum

\[\text{[mean, SNR, SFNR]} = [2688.6, 187.4, 188.4]\]

Raduis of Decorrelation

\[\text{rdc} = 8.9 \text{ pixels}\]
Smoothness - X

Smoothness (FWHM) in mm - X: [min mean max] = [2.075 2.200 2.473]

Smoothness - Y

Smoothness (FWHM) in mm - Y: [min mean max] = [2.396 2.483 2.781]
Smoothness - Z

Smoothness (FWHM) in mm - Z: [min mean max] = [1.672 2.251 2.702]

Center of Mass - X

Center of Mass in mm - X: [max displacement drift] = [0.012 0.008]
Center of Mass - Y

Center of Mass in mm - Y: [max displacement drift] = [0.065 0.063]

Center of Mass - Z

Center of Mass in mm - Z: [max displacement drift] = [0.025 -0.016]
Ghost

Mean of ghost voxels as % of non-ghost [masked] mean
(ghostmean, brightghostmean) = (2.172, 4.694)
(lower is better)

Odd-Even Difference Image