Measurements

<table>
<thead>
<tr>
<th>Measurements</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>mean signal (mean)</td>
<td>1472.1</td>
</tr>
<tr>
<td>Signal to Noise Ratio (SNR)</td>
<td>247.7</td>
</tr>
<tr>
<td>Signal to Fluctuation Ratio (SFNR)</td>
<td>239.0</td>
</tr>
<tr>
<td>Percent Fluctuation</td>
<td>0.05</td>
</tr>
<tr>
<td>Drift</td>
<td>0.32</td>
</tr>
<tr>
<td>Radius of Decorrelation (RDC)</td>
<td>8.6</td>
</tr>
<tr>
<td>Mean Ghost Percentage</td>
<td>1.966</td>
</tr>
<tr>
<td>Standard Deviation (std)</td>
<td>0.73</td>
</tr>
</tbody>
</table>

Signal

```plaintext
result.xml [percent fluct (trend removed), drift, driftfit] = [0.05, 0.32, 0].
```
Frequency Spectrum
(mean, SNR, SFNR) = 1472.1 247.7 239.0

Raduis of Decorrelation
rdc = 8.6 pixels
Smoothness -X

Smoothness (FWHM) in mm - X: [min mean max] = [2.156 2.286 2.494]

Smoothness -Y

Smoothness (FWHM) in mm - Y: [min mean max] = [2.453 2.586 2.751]
Smoothness -Z

Smoothness (FWHM) in mm - Z: [min mean max] = [1.602 2.094 2.722]

Center of Mass -X

Center of Mass in mm - X: [max displacement drift] = [0.025 0.018]
Center of Mass -Y

Center of Mass in mm - Y: [max displacement drift] = [0.052 0.050]

Center of Mass -Z

Center of Mass in mm - Z: [max displacement drift] = [0.018 0.018]
Ghost

Mean of ghost voxels as % of non-ghost [masked] mean
(ghostmean, brightghostmean) = (1.956, 5.147)
(lower is better)

Odd-Even Difference Image
SFNR Image